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9 **Displacement based seismic assessment for precast concrete frames**
10 **with non-emulative connections**

11
12 Mauro Torquati, Andrea Belleri¹, Paolo Riva

13 **Abstract**

14 The paper develops a methodology for the seismic vulnerability assessment, Displacement
15 Based Assessment (DBA), of one-storey and multi-storey precast concrete frames with non-
16 emulative connections. The method is based on the Direct Displacement Based Design procedure
17 initially developed by Priestley. The DBA is particularly suitable for the evaluation of the
18 seismic response of flexible structures, as it considers displacements as the leading parameters to
19 estimate the seismic vulnerability. The proposed procedure specifically accounts for the
20 influence of beam-column connections, P- Δ effects and second mode of vibration. The validation
21 has been performed by means of nonlinear time history analyses.
22

23 **Keywords:**

24 Displacement Based Assessment; Precast Structure; Non-emulative connections; Inelastic
25 Deflected Shape; P- Δ effects.
26

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27 **1. Introduction**

28 Precast construction technology is widely adopted thanks to the many advantages deriving from
29 its simplicity and versatility. In Italy, reinforced concrete (RC) precast buildings are commonly
30 used for industrial and commercial facilities, usually adopting non-emulative dry connections to
31 assemble the different elements. In areas not originally classified as seismic zones prior to 2004,
32 structures were not designed for seismic loads. For these types of buildings, the achievement of a
33 structural behaviour like cast in place RC buildings is difficult, unless the so called “emulative”
34 connections were used.

35 In the seismic assessment of existing buildings, the considered structures are generally treated as
36 hinged frames with cantilever columns fix-connected at the base, although the performance of
37 beam-column connections (Brunesi et al. 2015, Magliulo et al. 2015, Zoubek et al. 2013, Palanci
38 et al. 2017, Kremmyda et al. 2017) should be included in the assessment for a better estimation
39 of the structural vulnerability. The considered structures are very flexible and characterized by a
40 high seismic displacement demand because of large inter-storey heights and slenderness of the
41 columns. This leads to a seismic performance typically governed by the inter-storey
42 displacement control rather than by the limitation of material strains.

43 In the case of properly detailed connections and considering the high quality deriving from the
44 excellent standard achieved in the production process, precast structures could achieve high
45 performances in the case of earthquakes. However, due to a design carried out before the
46 enforcement of modern building code regulations and before an updated seismic zonation of the
47 Italian territory, many existing buildings are characterized by inadequate construction details and
48 poor seismic performance.

49 The high seismic vulnerability of existing precast buildings has been clearly highlighted by past
50 seismic events on the Italian territory (Toniolo and Colombo 2012, Magliulo et al. 2013, Belleri
51 et al. 2015a, Belleri et al. 2015b, Minghini et al. 2016, Clementi et al. 2016, among others). The
52 main damage patterns observed are associated with failure of structural and non-structural
53 connections, such as cladding panels (Scotta et al. 2015, Belleri et al. 2016), loss of beam
54 supports (Casotto et al. 2015, Ercolino et al. 2016), poor detailing in the columns and absence of
55 floor/roof diaphragm action. It is worth noting that failure of the connections was the factor
56 leading to most of the recorded collapses. Therefore, an accurate evaluation of the seismic
57 vulnerability of precast structures should account for precast connections.

58 In this paper, a seismic vulnerability assessment procedure is investigated. Such procedure,
59 namely Displacement Based Assessment (DBA), has been derived following the Direct
60 Displacement Based Design (DDBD) methodology initially developed by Priestley (Priestley
61 1997, Priestley et al. 2007) and extended to precast frame structures by Belleri (2017b). The
62 procedure considers building lateral displacements as the main parameters for the seismic
63 assessment of the structure (Sullivan and Calvi 2013, Welch et al. 2014, Landi et al. 2016,
64 Cardone 2016). The lateral displacement is a suitable seismic vulnerability indicator for the
65 considered buildings, due to the high deformability of the structural system combined with the
66 high deformation demand in the connection region.

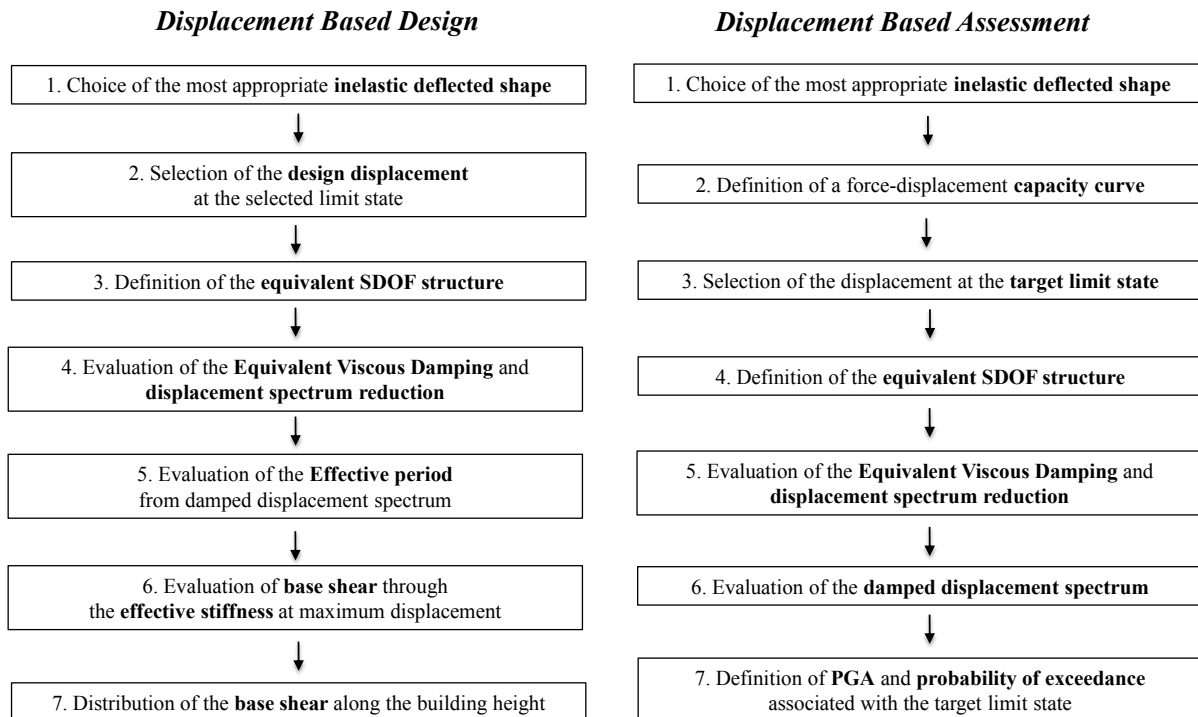
67 The procedure is developed for one-storey and multi-storey precast RC frames and accounts for
68 the main aspects influencing the seismic behaviour of the structure.,

69 The influence of non-emulative connections is specifically included in the definition of the
70 distribution of seismic forces and deformations, being the connections one of the most vulnerable

71 elements and the major cause of collapse of existing precast buildings. In addition, the influence
 72 of second order (P- Δ) effects and the second mode of vibration are directly considered.
 73 The proposed DBA procedure is applied to selected case studies representing a 3-storey frame of
 74 a multi-storey RC precast building. The results are validated by means of nonlinear time history
 75 analyses.

76 2. Displacement Based Assessment procedure

77 A vulnerability assessment procedure in accordance with the Direct Displacement Based Design
 78 approach (Priestley 1997, Priestley et al. 2007) is presented herein. Such an approach represents
 79 a more rational choice compared to typical force based design approaches, being structural
 80 damage strain related, and strains associated with displacements. A scheme of the DDBD
 81 approach is represented in **Figure 1**, the reader is referred to Priestley et al. 2007 and to Belleri
 82 (2017b) for the application to precast concrete structures. The DDBD considers a deflected shape
 83 representing the first inelastic mode of vibration; then an elastic equivalent single-degree-of-
 84 freedom (SDOF) structure is defined, with stiffness equal to the secant stiffness at maximum
 85 displacement. Based on the displacement ductility, the equivalent viscous damping (EVD) of the
 86 substitute system is defined and the elastic displacement spectrum at 5% damping is reduced
 87 accordingly; this allows obtaining the effective period of the equivalent SDOF system, the
 88 related stiffness and the base shear. The base shear is finally distributed along the building height
 89 and the load demand in the structural elements evaluated accordingly.



90
 91 *Figure 1 – Schematic representation of DBD and DBA procedures*

92 The DBA procedure is developed in accordance with the aforementioned principles (Figure 1).
 93 An in-depth explanation of the main steps is presented in the following. In addition, it is worth

94 noting that the DBA procedure could be applied in a different sequence of steps, to suit the
 95 engineer or structure in question, without affecting the core principles of the approach.

96 *Steps 1 to 3: from the inelastic deflected shape to the limit state selection*

97 In Step 1, an appropriate inelastic deflected shape is defined. The system non-linearity is
 98 examined to understand the most probable inelastic mechanisms. This step is particularly critical
 99 as it influences the entire procedure and its reliability, since it drives the definition of the
 100 parameters of the equivalent SDOF structure. Herein, two different methods are proposed for the
 101 definition of the inelastic deflected shape: the Pushover Method (PM) and the Equivalent
 102 Column Simplified Method (ECSM). In Step 2, a force-displacement capacity curve is derived
 103 from the obtained inelastic deflected shapes. In Step 3, a limit state corresponding to a point in
 104 the capacity curve is selected. Such limit state will be considered to estimate the probability of
 105 exceedance.

106 The base shear and the lateral displacement at each floor are evaluated at yielding of the system
 107 ($V_y, \Delta_{y,i}$) and at the selected limit state ($V_u, \Delta_{u,i}$). The PM and ECSM procedures are described
 108 in the next section.

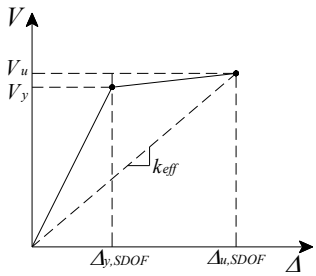
109 *Step 4: Substitute structure parameters*

110 The parameters of the equivalent SDOF structure are defined in **Table 1**.

111 **Table1** - Definition of the parameters of the equivalent SDOF structure

112 Note: m_i is the mass of the i^{th} floor;

113 $\Delta_{y,i}, \Delta_{u,i}$ are the displacements at yield and at the selected limit state for the i^{th} floor, respectively.

Yield displacement	$\Delta_{y,SDOF} = \frac{\sum m_i \cdot \Delta_{y,i}^2}{\sum m_i \cdot \Delta_{y,i}} \quad (1)$
Target displacement	$\Delta_{u,SDOF} = \frac{\sum m_i \cdot \Delta_{u,i}^2}{\sum m_i \cdot \Delta_{u,i}} \quad (2)$
Effective mass	$m_{eff} = \frac{\sum m_i \cdot \Delta_{u,i}}{\Delta_{u,SDOF}} \quad (3)$
Secant stiffness at target displacement	$k_{eff} = \frac{V_u}{\Delta_{u,SDOF}} \quad (4)$ 
Effective period	$T_{eff} = 2\pi \sqrt{\frac{m_{eff}}{k_{eff}}} \quad (5)$

115 *Step 5: Equivalent viscous damping (EVD) and Displacement Spectrum reduction*

116 The equivalent structure corresponds to an elastic SDOF system with a fundamental period of
117 vibration (T_{eff}) obtained from considering the secant stiffness of the inelastic structure at
118 maximum displacement ($\Delta_{u,SDOF}$). The EVD of the equivalent structure is associated with the
119 hysteretic energy dissipation of the structural system (Priestley et al. 2007, Dwairi et al. 2007,
120 Grant et al. 2004, Belleri 2017b). In the case of RC structures, the material nonlinearity is well
121 captured by the Takeda (Otani 1974) model, whose corresponding EVD (ξ_{eq}) is a function of the
122 displacement ductility μ_{Δ} , defined as $\Delta_{u,SDOF}/ \Delta_{y,SDOF}$:

$$123 \quad \xi_{eq} = 0.05 + \alpha \left(\frac{\mu_{\Delta} - 1}{\mu_{\Delta} \pi} \right) \quad (6)$$

124 where α depends on the structural system (e.g. frame buildings or wall buildings). **Eq.6** allows
125 obtaining a damped displacement spectrum ($S_{D,in}$) accounting for viscous damping values
126 different from 5%:

$$127 \quad \eta = \frac{S_{D,in}(T, \xi_{eq})}{S_{D,el}(T, \xi = 0.05)} = \sqrt{\frac{0.05 + z}{z + \xi_{eq}}} \quad (7)$$

128 It is important to highlight that the coefficients α and z in **Eq.6** and **Eq.7** depend on the ground
129 motion set used in the calibration of each equation; nonetheless, when the equations are
130 combined, independent results are obtained if the same ground motion set is used in the
131 calibration of each equation (Pennucci et al. 2011). Therefore, considering the formula for the
132 damped displacement spectrum contained in EN 1998-1 (i.e. **Eq.7** with $z=0.05$), the
133 corresponding values of α are 0.635 and 0.808 for wall and frame buildings, respectively. Such
134 values have been obtained from Priestley et al. (2007) by means of a least square regression
135 analysis; indeed, the values of α (0.444 and 0.565 for the wall and frame buildings, respectively)
136 contained in Priestley et al. (2007) are associated with $z=0.02$ in **Eq.7**.

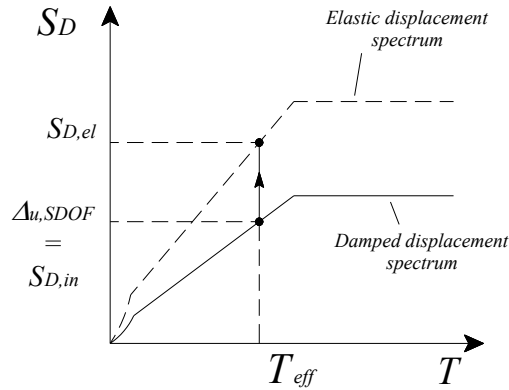
137 The present paper considers **Eq.7** with $z=0.05$ and **Eq.6** with $\alpha=0.635$. The deflected shape and
138 energy dissipation capacity of the structural typology under investigation (i.e. non-emulative
139 beam-column connections) are closer to wall buildings rather than frame buildings. **Eq.6** is
140 considered appropriate for a first estimate of EVD. For a refined EVD estimate, including the
141 peculiar hysteretic shape of beam-column connections, a detailed evaluation should be carried
142 out, following for instance what reported in Belleri (2017b) or other algorithms.

143 *Step 6 and 7: Damped displacement spectrum and probability of exceedance*

144 $\Delta_{u,SDOF}$ and T_{eff} identify a point in the damped displacement spectrum (**Figure 2**). The related
145 elastic displacement spectrum is obtained from **Eq.6** and **Eq.7** (Step 6). Once the elastic
146 displacement spectrum has been defined, the probability of exceedance associated with the
147 selected limit state is obtained from building code formulations, as in EN 1998-1 (Step 7).

148 To account for uncertainty in the DBA procedure (Sullivan and Calvi, 2013), the simplified
149 procedure proposed by Fajfar and Dolsek (2012) could be adopted. Finally, P- Δ effects and the
150 second mode of vibration influence the response of the equivalent SDOF system; to account for
151 such effects in the DBA approach, specific procedures have been developed and addressed in the
152 following.

153



154

155

Figure2 – Relationship between elastic and damped displacement spectrum

156

3. Displacement profile and capacity curve definition

157 The definition of the probable displacement profile of the structure in the non-linear range
 158 represents one of the key steps in the DBA procedure. Priestley et al. (2007) provided
 159 formulations for the definition of the inelastic deformed shape for the most common structural
 160 systems. Such formulations are suitable for the design of new structures, where capacity design
 161 enforces the structure to behave in a controlled ductile manner. In the case of existing structures
 162 not designed following modern anti-seismic approaches, as the construction typology analysed
 163 herein, a simplified estimation of the displacement profile represents a critical task. In addition, it
 164 is worth noting that the connections between the elements may influence the nonlinear behaviour
 165 of the whole system: indeed, beam-column connections could significantly affect the inelastic
 166 displacement distribution, with possible displacement compatibility issues between the
 167 connected elements (Belleri et al. 2014, Belleri et al. 2015b, Belleri et al. 2016).

168 This paper proposes two methods to obtain the displacement profile of existing precast structures
 169 with non-emulative connections: an accurate approach (Pushover Method - PM), requiring non-
 170 linear finite element analyses, and a simpler approach (Equivalent Column Simplified Method -
 171 ECSM), based on simplified assumptions and formulations. It is worth noting that in the absence
 172 of mechanical connections between beams and columns or between floor elements and
 173 supporting beams, i.e. connections relying on friction, specific time history analyses should be
 174 carried out including the vertical component of the ground motion to evaluate the possibility of
 175 loss of support.

3.1 Pushover Method (PM)

177 In the first method, the definition of the inelastic deflected shape is performed by means of
 178 classical or adaptive pushover analyses. The non-linear behaviour of both RC structural elements
 179 and connections is directly accounted for, being the latter specifically addressed in the next
 180 section. The resulting capacity curve, in terms of base shear versus roof displacement, is
 181 bilinearized according to current standards (herein EN 1998-1). This allows defining the
 182 displacement and base shear at yield (Δ_y, V_y) and at the target limit state (Δ_u, V_u). The associated
 183 floor displacements ($\Delta_{y,i}$ and $\Delta_{u,i}$) are recorded and the equivalent SDOF structure is defined as
 184 described in the previous section.

185 A nonlinear finite element model allows accounting for specific aspects not considered in the
186 following simplified approach (ECSM), as for instance the diaphragm flexibility and the
187 presence of infills (masonry infills and cladding panels interacting with the structure). The
188 diaphragm flexibility is directly evaluated in the pushover analysis by a three-dimensional finite
189 element model including the connections between floor elements and the possible RC cast-in-
190 place topping. Regarding masonry infills, they can be considered by means of simplified struts as
191 in El-Dakhakhni et al. 2003, Crisafully and Carr 2007, and Rodrigues et al. 2010 among others.
192 In the case of external precast cladding panels, the panel-structure connections are typically
193 characterized by high vulnerability due to lack of in-plane displacement compatibility of the
194 connecting system (Brunesi et al. 2015, Belleri et al. 2016, Zoubek et al. 2016, Toniolo and Dal
195 Lago 2017), which leads to a generally low bracing contribution. Therefore, in such conditions, a
196 prediction of the performance of the cladding panel connections could be carried out without
197 modelling the connecting system but just considering the relative displacements between the
198 connecting points.

199 *3.2 Equivalent column simplified method (ECSM)*

200 ECSM has been developed to provide a faster and simplified evaluation of the displacement
201 profile of one-storey, two-storey and three-storey precast frames under seismic loading without
202 requiring finite element modelling. The following assumptions apply:

- 203 i. the columns are continuous up to the roof;
- 204 ii. the beams flexure stiffness is much higher than the joint rotational stiffness (i.e. the
205 flexural deformations are lumped at the beam-column non-emulative connection);
- 206 iii. the post-yield stiffness of columns and connections is zero;
- 207 iv. all the connections are considered yielded after first yielding of any connection.

208 The simplified procedure leads to the definition of an approximate capacity curve for planar
209 frames, therefore it is not intended to capture three-dimensional effects such as those related to
210 diaphragm flexibility or the influence of rigid infills, which require more refined analyses.
211 However, this procedure has the advantage of not requiring finite element analyses, because it is
212 based on the step by step application of analytical formulations. The procedure can be
213 implemented in spreadsheets and can be seen as a seismic screening tool for a rapid assessment
214 of the structural vulnerability. In general, seismic screening has the advantage of highlighting
215 potential seismic deficiencies and it is adopted both to rank the seismic vulnerability of buildings
216 among a portfolio and to get a preliminary estimate of the seismic risk of a given building.
217 FEMA 154 and ASCE/SEI 41 are examples of seismic screening procedures. ECSM considers
218 an equivalent column system. **Figure 3** shows the schemes used to represent one-storey, two-
219 storey and three-storey precast frames. ECSM assumes that the behaviour of the building can be
220 represented by a planar model. Displacement amplifications due to accidental eccentricity could
221 be added in the same way of building code formulations.

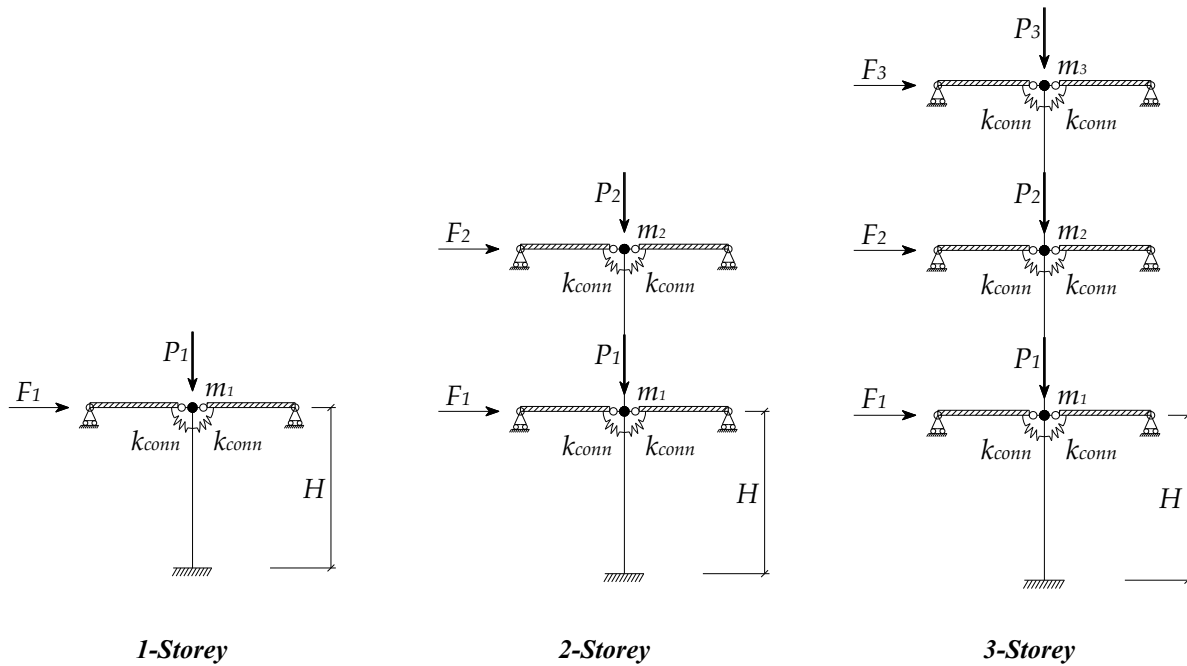


Figure 3 –Simplified schemes considered for the application of the procedure
 Note: F_i is the storey load proportional to the first mode eigenvector;
 P_i and m_i are the floor vertical load and the seismic mass, respectively;
 k_{conn} is the stiffness of beam-column connections

222
 223
 224
 225

226 **Step 1: Lateral load distribution**

227 The lateral load distribution is related to the fundamental vibration mode of the building. The
 228 rotational stiffness of the beam-column joints is initially neglected, as in an ideal hinged-frame
 229 structure; in this configuration the lateral load resisting systems is made of cantilever columns.
 230 The horizontal forces F_i on the system are proportional to $\phi_i m_i$, where m_i is the floor mass and ϕ_i
 231 corresponds to the i^{th} eigenvector component of the first mode of vibration of the considered
 232 equivalent column. In the case of a continuous column with constant cross-section, constant
 233 inter-storey height and constant floor-mass, the eigenvector of the fundamental mode is
 234 independent from the column height and column cross-section. In such case, the eigenvector
 235 components are reported in **Figure 4**.

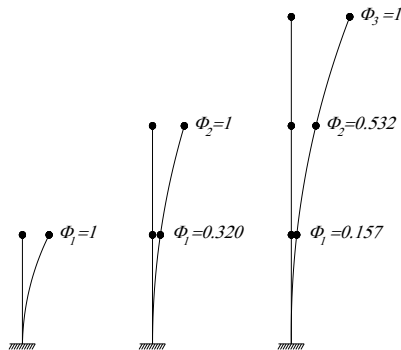
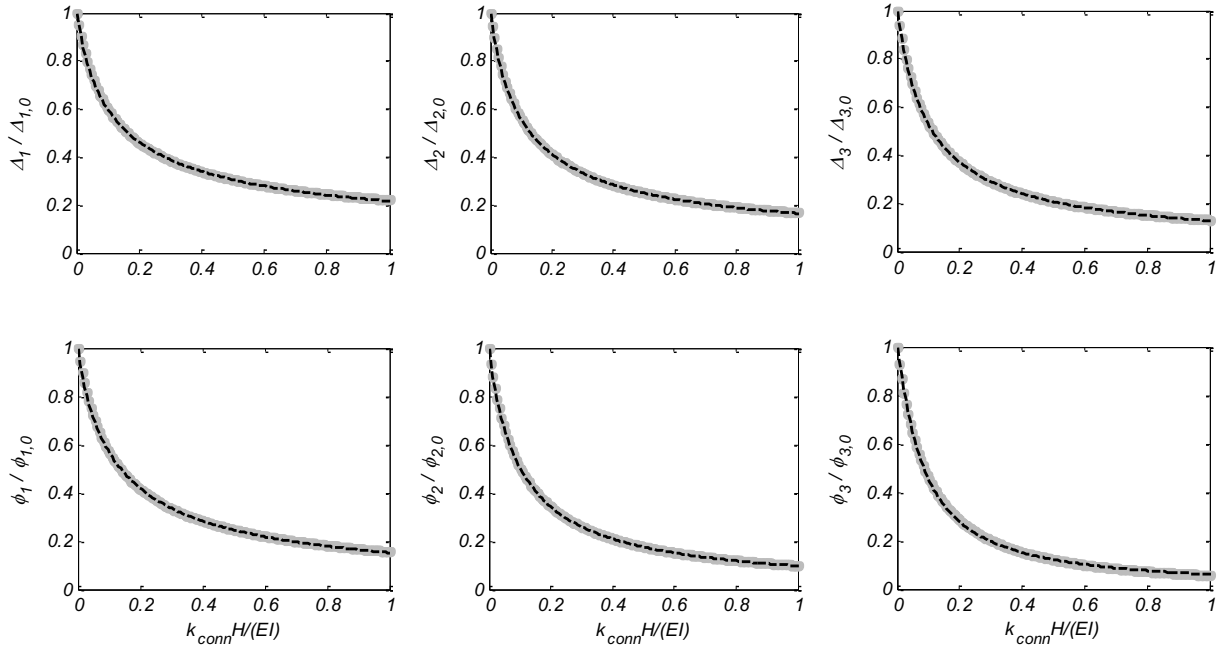


Figure 4 – Eigenvectors of cantilever column for one-storey, two-storey, and three-storey

236
 237
 238

239 *Step 2: Influence of beam-column connections*

240 The influence of beam-column connections on displacements and rotations is considered herein.
 241 Reference is made to the values obtained from the hinged-frame column mentioned in the
 242 previous step. A parametric analysis has been performed to define displacements and rotations as
 243 a function of the connection stiffness, considering the lateral load distribution proportional to the
 244 eigenvector accounting for the connection stiffness. **Figure 5** shows the results of the analyses in
 245 terms of displacements and rotations at each floor (Δ_i , φ_i , respectively) in dimensionless form. In
 246 the figure, displacements and rotations obtained from a load distribution according to the first
 247 mode of vibration including connection stiffness are normalized to those corresponding to the
 248 cantilever column case ($\Delta_{i,0}$, $\varphi_{i,0}$) obtained from a load distribution according to the first mode of
 249 vibration depicted in **Figure 4**; it is worth noting that the former load distribution has been
 250 previously scaled in order to have the same base shear of the latter. The connection stiffness
 251 (k_{conn}) is normalized by $(EI)/H$, where H , E and I are the inter-storey height, the modulus of
 252 elasticity and the second moment of area of the column, respectively. The results have been
 253 obtained from solving the simplified scheme of **Figure 3** by the direct stiffness method.



254
 255 **Figure 5** – Parametric analyses assessing the influence of connection stiffness on displacements and rotations

256 The dimensionless form allows simplifying the data fitting. The curves shown in **Figure 5** have
 257 been fitted by the following equations, whose graphic representation is shown in dashed line in
 258 the same figure:

$$\frac{\Delta_{i,conn}}{\Delta_{i,0}} = \frac{l}{\left(\frac{k_{conn} \cdot H}{E \cdot I}\right)^m + l} + n \quad (8)$$

259

$$\frac{\varphi_{i,conn}}{\varphi_{i,0}} = \frac{p}{\left(\frac{k_{conn} \cdot H}{E \cdot I}\right)^q + p} \quad (9)$$

260

261 The coefficients l , m , n , p and q are reported in **Table 2**. All the coefficients have been
 262 determined by means of linear least square regression. The analytical expressions of
 263 displacements and rotations for the cantilever column ($\Delta_{i,0}$ and $\varphi_{i,0}$) under the lateral load
 264 distribution proportional to the first eigenvector (**Figure 4**) are presented in **Table 3**. Such values
 265 have been obtained from applying the direct stiffness method.

266 Therefore, it is possible to obtain column displacements and rotations from the values of the
 267 cantilever column case (**Table 3**) directly through **Eq.8** and **Eq.9**.

268

Table 2 – Coefficients for Eq. 8 and Eq. 9

n. Storey	Floor	l	m	n	p	q
3	3	0.1194	0.9290	0.0216	0.0643	1.1096
	2	0.1510	0.8655	0.0335	0.1081	0.9779
	1	0.1989	0.7852	0.0501	0.1792	0.8656
2	2	0.2510	0.8859	0.0261	0.1499	1.0618
	1	0.3439	0.7869	0.0419	0.2649	0.9206
1	1	0.8966	0.7855	0.0235	0.5	1

269

Table 3 – Displacements and rotations for the cantilever column case according to force distribution in Figure 4

270

Note: F is the force applied at the roof level

n. Storey	Floor	Δ $\left(\frac{FH^3}{3EI}\right)$	φ $\left(\frac{FH^2}{2EI}\right)$
3	3	35.076	11.285
	2	18.649	10.285
	1	5.487	6.753
2	2	8.800	4.320
	1	2.820	3.320
1	1	1	1

271

272 The approximation provided by **Eq.8** and **Eq.9** leads to a maximum error of 5% and 8%,
 273 respectively. In the case the inter-storey height of the first floor is 30% higher than the other
 274 floors, the maximum errors become 11% and 22%, respectively. In such a case, Eq.8 and Eq.9
 275 are evaluated considering the mean inter-storey height, while the floor displacements are
 276 estimated from a linear interpolation of the displacements obtained from the equal inter-storey
 277 height case. It is also worth noting that the maximum errors obtained from considering a 50%
 278 mass reduction at the roof level are 6% and 11%, respectively; this situation is intended to
 279 account for the presence of micro-shed elements and/or skylights on the roof. All the

280 aforementioned errors are referred to $k_{conn} H/(EI)$ less than 1, which is considered an upper bound
 281 for the structural typology under investigation.

282 *Step 3: Capacity curve definition*

283 The relationship between the lateral loads, displacements and rotations allows defining an
 284 approximate capacity curve of the building (**Figure 6**).

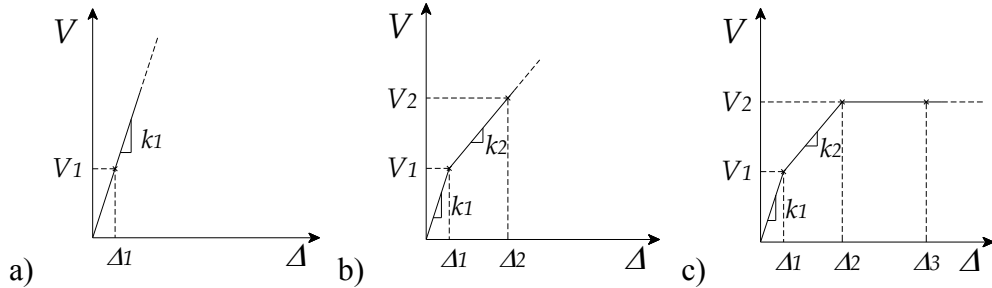


Figure 6 – *Approximated capacity curve construction.*

Note: V is the base shear of the system (sum of horizontal forces F_i); Δ is the roof displacement.

288 The capacity curve is obtained from the following steps:

- 289 a) increase the lateral loads F_i (proportional to the first mode eigenvector, **Figure 4**) until
 290 first yielding of the column base or beam-column connection, whichever occurs first. Such
 291 condition defines the point (V_1, Δ_1) ;
- 292 b) neglect the stiffness of the yielded elements and increase the lateral loads until yielding of
 293 the other type of element (beam-column connection or column base). This condition
 294 defines the point (V_2, Δ_2) ;
- 295 c) keep the base shear constant up to a displacement and rotation corresponding to the failure
 296 of an element, following the linear deflected shape of **Figure 7**. The displacements and
 297 rotations in **Figure 7** must be added to the corresponding values reached in the previous
 298 step (i.e. those corresponding to V_2, Δ_2 in **Figure 6**).

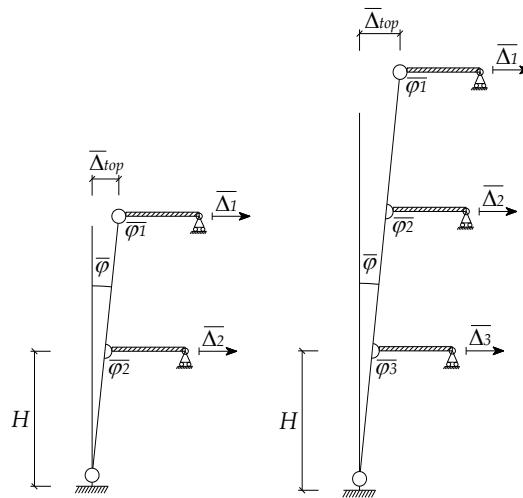


Figure 7 – *Rigid rotation of the system corresponding to step c) of the approximated curve definition.*

301 The capacity curve of the whole system is obtained from summing the contribution of each
 302 column. Given the capacity curve, the DBA procedure follows the steps previously described.

304 4. Beam-column connections

305 The hysteretic behaviour of beam-column connections is obtained from considering an analytical
306 expression for the shear-displacement relationship. In the literature, various formulations are
307 available (CNR 10025, Doneux et al., 2006; Ferreira, 1999; Soroushian et al., 1987, Vintzeleou
308 and Tassios, 1987; Tsoukantas and Tassios, 1989). This paper adopts the formulation proposed
309 by Ferreira (1999) which allows accounting for the pretension of dowels and the presence of an
310 elastomeric bearing.

311 The considered force-displacement relationship considers three contributions influencing the
312 global deformation of the connection:

- 313 a) the deformation of the bar embedded in the concrete (column side);
- 314 b) the deformation of the bar embedded in the grout (beam side);
- 315 c) the shear deformation of the elastomeric bearing.

316 The resulting shear-displacement relationship is a tri-linear curve, whose analytical definition is
317 highlighted in the Appendix.

318 The moment-rotation behaviour of the connection is evaluated for clockwise (**Figure 8a**) or
319 counter-clockwise (**Figure 8b**) bending moments, due to the possible asymmetric position of the
320 dowels in the column corbel and to the possible contact between the top of the beam and the
321 column.

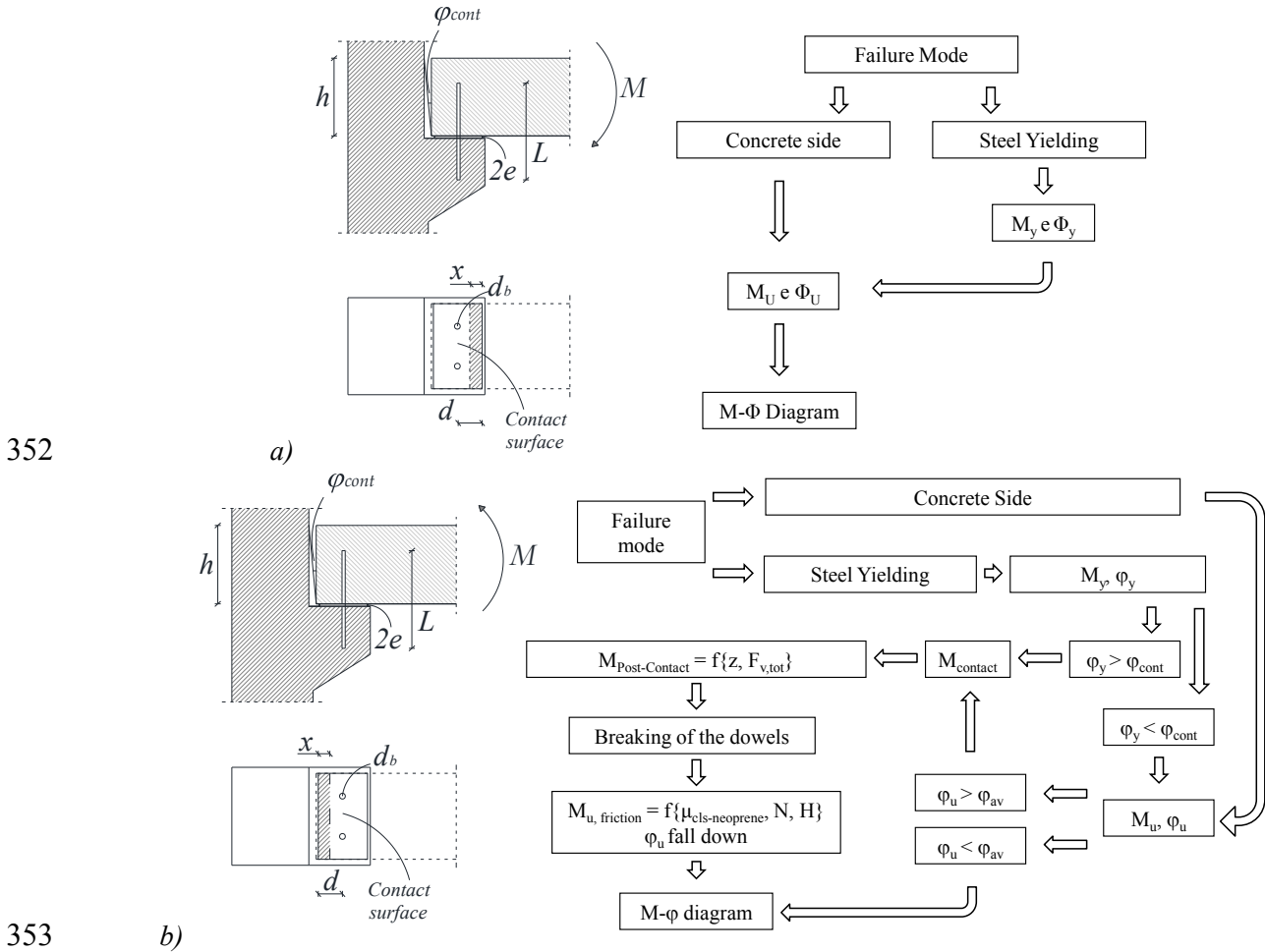
322 For clockwise bending moment, there is no contact between the top of the beam and the column.
323 A cross-section analysis is conducted considering the cross-section defined by the beam-column
324 interface and a compressive force resulting from the gravity loads and the dowel pretension. The
325 connection failure is associated with either the tension failure of the dowels or bearing failure of
326 the concrete, whichever happens first. If yielding of the dowels in tension happens before the
327 connection failure, the moment-rotation diagram is defined by two points: the first point
328 corresponds to yielding of the dowels, the second point to failure of the connection. The
329 elongation of the dowels at yielding and at failure allows defining the connection rotation.

330 For counter-clockwise bending moment, the first step considers the evaluation of the failure
331 mode of the connection as in the case of clockwise bending moment. A first estimate of the
332 moment-rotation points is obtained from assuming no contact between the beam and the column.
333 The following step evaluates the effects associated with the contact between the top of the beam
334 and the column. Three situations are possible:

- 335 a) the contact is reached before yielding of the dowels;
- 336 b) the contact is reached before connection failure;
- 337 c) no contact until connection failure.

338 The moment-rotation diagram evaluated in the first step (i.e. considering no contact between the
339 beam and the column) is valid only for rotations smaller than the contact rotation. After beam-
340 column contact, the connection is subjected to a stiffness increase. The post-contact bending
341 moment is obtained from the product of the shear resistance of the connection (i.e. from the
342 force-displacement curve) and the resulting lever arm, herein assumed equal to $0.9h$. After shear
343 failure of the connection, the beam can still rotate with a bending moment given by the product
344 of the concrete-neoprene friction force and the lever arm. Such condition is not considered herein
345 due to the uncertainty in the response, as for instance related to the influence of the vertical
346 component of the earthquake. The Appendix contains a calculation example for the
347 aforementioned formulation.

348 In the present paper, the moment-rotation and force-displacement relationship of the beam-
 349 column connections are directly included in the finite element models by means of one rotational
 350 spring and one translational spring, respectively. **Figure 9** shows a possible modelling strategy
 351 able to account for the coupled translational-rotational behaviour of beam-column connections.



353
 354 **Figure 8 – Beam-column connection behaviour:**
 355 a) clockwise bending moment; b) counter-clockwise bending moment.

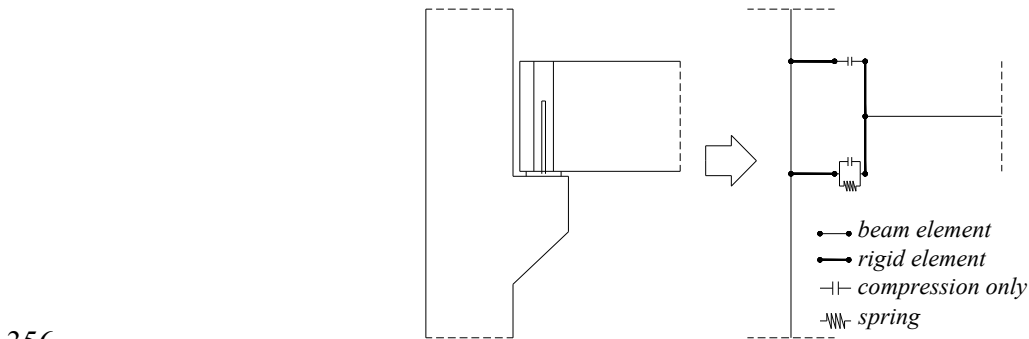
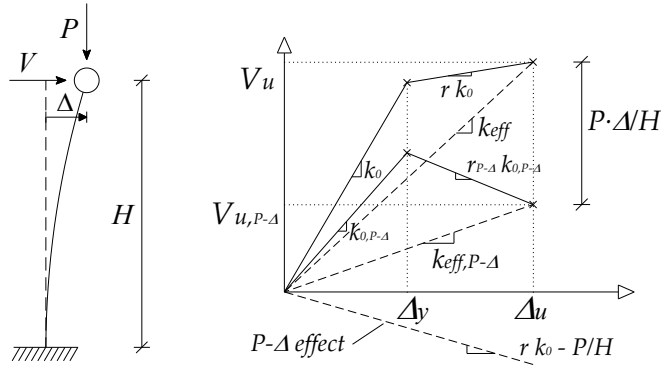


Figure 9 – Alternative modelling scheme for beam-column connections.

359 **5. P-Δ effects**

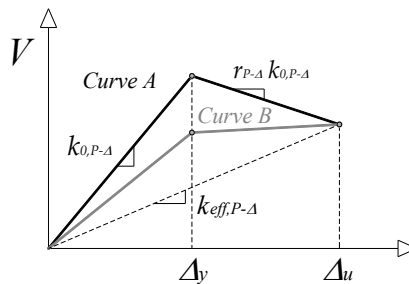
360 During an earthquake, second order P-Δ effects could significantly increase the horizontal
 361 displacements achieved by a structure and therefore need to be accounted for in a seismic
 362 assessment procedure. The methodology proposed in Belleri et al. (2017a) is considered herein.
 363 Such procedure is briefly summarized in the following.
 364 In the first step, the capacity curve is reduced to account for second order effects (**Figure 10**).
 365 The bilinearization of the capacity curve needs to allow for negative post-yield stiffness.



366

367 **Figure 10** – Influence of P-Δ effects on the structural response of a SDOF system

368 In the second step the EVD of the equivalent SDOF system is adjusted. It is worth mentioning
 369 that the available EVD formulations (as for instance Grant et al. 2004, Priestley et al. 2007) have
 370 been calibrated based on the force-displacement response of inelastic SDOF systems with
 371 positive post yield stiffness ratio (r), typically $r = 0.05$. Therefore, given Δ_u , the actual SDOF
 372 system response considering P-Δ effects is represented by Curve A in **Figure 11**, while the actual
 373 curve considered in the EVD formulation is represented by Curve B, leading to a net hysteretic
 374 energy underestimation and consequently EVD underestimation. It is worth noting that to
 375 account for P-Δ effects in the DBD procedure, Priestley et al. (2007) recommended to adjust the
 376 base-shear with a specific coefficient which depends on the hysteretic system but also on the
 377 main characteristics of the ground motions. Indeed, the hysteretic energy that might be
 378 underestimated is offset by dynamic ratcheting that is more significant for non-linear systems
 379 with high P-Δ loads (Priestley et al., 2007).



380

381 **Figure 11** – Curve A: SDOF response including P-Δ effects; Curve B: SDOF response used in EVD formulation

382 Herein, **Eq.7** is modified by means of a correction factor (λ) to account for differences in the
 383 hysteretic energy estimation:

384
$$\eta_{P-\Delta} = \sqrt{0.10 / (0.05 + \lambda \cdot \xi_{eq} \text{ } r=0.05)}$$
 (10)

385 Where $\eta_{P-\Delta}$ represents the ratio between the damped displacement spectrum including P- Δ
 386 effects ($EVD = \lambda \cdot \xi_{eq} \text{ } r=0.05$) and the elastic displacement spectrum ($EVD = 0.05$). For the
 387 considered structural typology, λ is:

388
$$\lambda(r_{P-\Delta}, \mu_{\Delta}) = (4.57 \cdot \mu_{\Delta} - 5.53)(r_{P-\Delta}^2 - 0.0025) - (1.19 \cdot \mu_{\Delta} - 0.80)(r_{P-\Delta} - 0.05) + 1$$
 (11)

389 The correction factor λ has been derived from a parametric analysis considering different values
 390 of post-yield stiffness ratio, system ductility and effective period. A series of non-linear dynamic
 391 analyses of SDOF systems allowed the calibration of the coefficients of **Eq.11** by means of non-
 392 linear regression analyses (Belleri et al., 2017a).

393 **6. Influence of the second mode of vibration**

394 The beam-column connection is a critical detail of existing precast structures. Therefore, the
 395 seismic demand in terms of connection rotation must be carefully evaluated. The displacement
 396 profile considered in the DBA procedure is obtained from the PM or ECSM method. In both
 397 approaches, the target limit state is evaluated from a force distribution proportional to the first
 398 mode of vibration, not accounting for higher modes of vibration. This could lead to possible
 399 underestimation of the connection rotation demand.

400 Various methods have been developed to consider the influence of higher modes of vibration in
 401 non-linear static analyses, such as the Modal Pushover Analysis developed by Chopra and Goel
 402 (2002) and the extended N2 method proposed by Kreslin and Fajfar (2011). In the framework of
 403 displacement based design, Priestley et al. (2007) proposed a method to predict the shear force
 404 and moment envelopes in the structural elements accounting for higher modes of vibration. This
 405 method, known as modified modal superposition (MMS), considers a modal combination (such
 406 as the square root of the sum of squares, SRSS) in which the shear and moment distribution of
 407 the first mode are taken from the displacement based design procedure and the corresponding
 408 distribution of the higher modes are taken from an elastic response spectrum analysis. Sullivan et
 409 al. (2008) highlighted the influence of higher modes in ductile structures.

410 The method considered herein is an extension of MMS for the assessment of existing structures.

411 The proposed approach is based on the following assumptions:

- 412 i. the first mode of vibration is the predominant mode in terms of inelastic displacement
- 413 distribution;
- 414 ii. only the influence of the second mode of vibration is considered to refine the results
- 415 obtained from the DBA procedure;
- 416 iii. all the hysteretic energy dissipation is associated with the first mode of vibration; the
- 417 second mode is considered elastic.

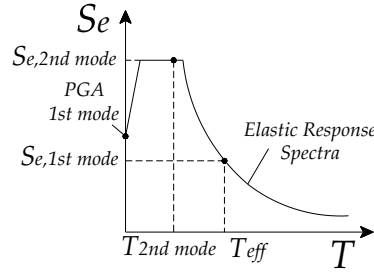
418 The procedure is described in the following steps.

419 *Step 1: Application of the DBA procedure*

420 The DBA procedure is applied to the structure, considering the inelastic displacement profile
 421 obtained from a force distribution proportional to the first mode of vibration. The DBA
 422 procedure allows the definition of the peak ground acceleration associated with the first mode of
 423 vibration ($PGA \text{ } 1^{st} \text{ mode}$). The corresponding forces/deformations are recorded as R_I .

424 *Step 2: Elastic response spectrum of the 2nd mode of vibration*

425 The influence of the 2nd mode of vibration is evaluated by means of an elastic modal analysis
 426 accounting for the sole second mode. The *PGA 1st mode* (Step 1) allows defining the elastic
 427 spectrum ($\xi=5\%$) used to identify the spectral acceleration ($S_{e,2nd\ mode}$) associated with the second
 428 mode of vibration ($T_{2nd\ mode}$ in **Figure 12**). The modal analysis is performed placing elastic
 429 rotational springs at the beam-column connections and at the column base; for this the secant
 430 stiffness for each connection is considered. The secant stiffness is calculated as the ratio between
 431 the flexural moment and the rotation associated with the considered limit state.
 432



433

434 **Figure 12** – Evaluation of the spectral acceleration of the second mode of vibration ($S_{e,2nd\ mode}$).

435 The effects in terms of forces/deformations obtained from the modal analysis are combined
 436 following the SRSS rule with the results of Step 1 (R_1). The combined results are referred to as
 437 R_2 .

438 *Step 3: Definition of a correction factor*

439 A correction factor c_f is defined:

$$440 \quad c_f = R_{1,c} / R_{2,c} \quad (12)$$

441 $R_{1,c}$ and $R_{2,c}$ are the deformations/forces for the critical element obtained from Step 1 and Step 2,
 442 respectively; the critical element is the element associated with the definition of the target limit
 443 state. The target displacement Δ_u defined in the DBA procedure is reduced by the correction
 444 factor c_f ; the new target displacement ($\Delta_{u,2}$) is

$$445 \quad \Delta_{u,2} = c_f \cdot \Delta_u \quad (13)$$

446 *Step 4: DBA procedure including 2nd mode effects*

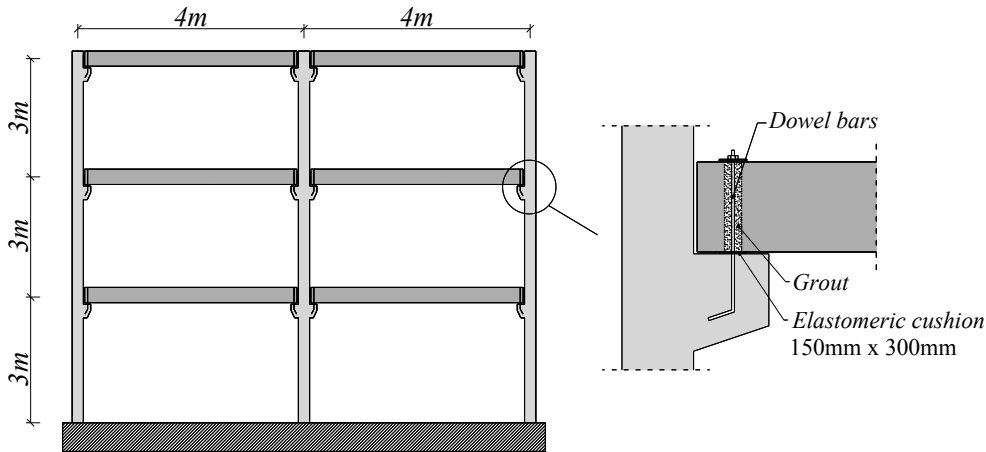
447 The properties of the equivalent structure are redefined according to $\Delta_{u,2}$ and a new point
 448 associated with the target limit state ($V_{u,2}, \Delta_{u,se2}$) is estimated following the DBA procedure.
 449 Iterations between Step 1 and Step 4 may be required until convergence.

450 It is worth noting that only the second mode of vibration is considered herein. The contributions
 451 of other relevant modes of vibration could be included in a similar way.

452 **7. DBA procedure for selected case studies**

453 The proposed DBA procedure is validated considering two planar frames (Case Study A and
 454 Case Study B) representative of three-storey precast buildings. The seismic vulnerability is
 455 evaluated in terms of the peak ground acceleration on rock (a_g) associated with the target limit
 456 state. The proposed seismic assessment methods (DBA-ECSM and DBA-PM) are considered
 457 and compared to the results obtained from non-linear dynamic analyses (Incremental Dynamic
 458 Analyses, IDA).

459 Figure 11 shows the geometry for Case Study A. The frame is composed by 6 beams with
 460 rectangular cross section (300x500 mm), 3 columns with a total height equal to 9 m and square
 461 cross section (350x350 mm). The concrete compressive strength is 50 MPa, while the grout
 462 surrounding the dowels has a compressive strength of 59 MPa. The steel yield strengths are
 463 480 MPa and 340 MPa for the column rebars and the connection dowels, respectively. The
 464 column longitudinal reinforcement is made by 8 rebars (24mm diameter). The resulting bending
 465 moment capacity is 327 kNm considering an axial load equal to 472 kN. The beam-column
 466 connection is made of two dowels (12mm diameter) with a supporting neoprene cushion (5 mm
 467 thick) (**Figure 13**). A seismic mass equal to 75,000 kg is considered at each floor of the frame.
 468 Soil-structure interaction is not accounted for and the columns are assumed fixed to the ground.
 469 Regarding EVD, the contribution of the beam-column connection has been neglected herein, due
 470 to the low dissipation capacity of the connection compared to the plastic hinge at the column
 471 base. Case Study B differs from Case Study A in that the column cross-section is bigger
 472 (600x600mm,) and the stiffness of the beam-column connection is 4 times higher than Case
 473 Study A. The column longitudinal reinforcement is made by 16 rebars (18mm diameter) which
 474 leads to a bending moment capacity equal to 1005 kNm.
 475



476
 477

Figure 13 – Geometry of the considered frame.

478 *7.1 DBA with the Equivalent Column Simplified Method (DBA-ECSM)*

479 The capacity curve is obtained from following the ECSM method. First, the displacements and
 480 rotations of the cantilever column are calculated from **Table 3** following an arbitrary lateral load
 481 distribution proportional to the first mode of vibration (**Figure 4**). Such arbitrary loads (25.0 kN,
 482 13.3 kN and 3.9 kN for 3rd, 2nd, and 1st floor, respectively) allow defining the initial elastic
 483 branch of the capacity curve.

484 Considering a beam-column connection stiffness (k_{conn}) equal to 2480 kNm/rad and
 485 10000 kNm/rad for Case Study A and Case Study B respectively, the resulting values of the ratio

486 $k_{\text{conn}}/(EI/H)$ are 0.159 and 0.074, respectively. The column lateral displacements and rotations
 487 accounting for the beam-column connection stiffness (**Table 4**) are obtained from **Eq.8** and
 488 **Eq.9**.

489 **Table 4** – Displacements and rotations for the cantilever case with and without beam-column connections

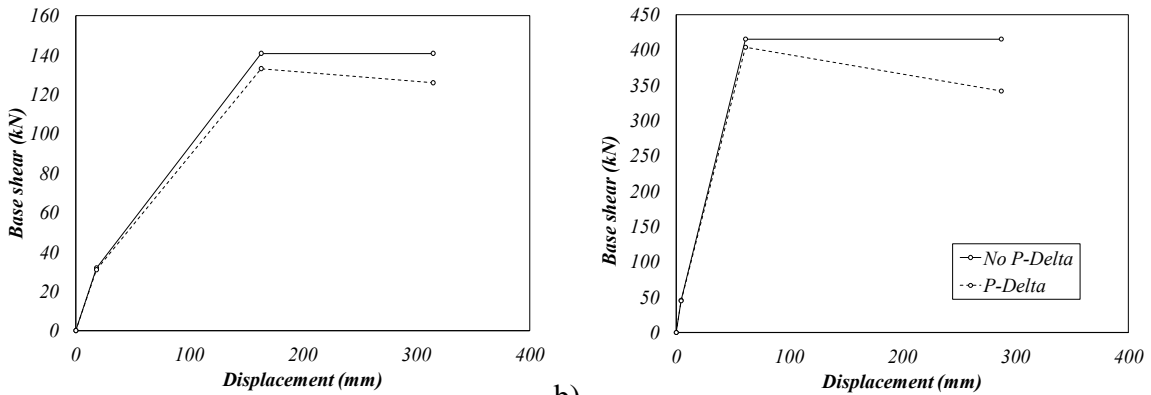
Storey	Case study A				Case study B			
	$\Delta_{i,0}$ (mm)	$\Delta_{i,\text{conn}}/\Delta_{i,0}$	$\varphi_{i,0}$ (rad)	$\varphi_{i,\text{conn}}/\varphi_{i,0}$	$\Delta_{i,0}$ (mm)	$\Delta_{i,\text{conn}}/\Delta_{i,0}$	$\varphi_{i,0}$ (rad)	$\varphi_{i,\text{conn}}/\varphi_{i,0}$
3	168.7	43.0%	0.0271	34.3%	19.5	60.8%	0.0031	55.2%
2	89.7	47.4%	0.0247	40.6%	10.4	64.5%	0.0029	58.8%
1	26.4	52.7%	0.0162	48.5%	3.1	69.2%	0.0019	65.1%

490
 491 The lateral loads are then increased until failure of the first connection. The second branch of the
 492 capacity curve is obtained from considering a residual stiffness of the system equal to the column
 493 stiffness without beam-column connections. The lateral loads are further increased until yielding
 494 of the column base. The last branch of the curve is obtained increasing displacements and
 495 rotations linearly until failure of the first connection or until a selected limit state. Table 5 shows
 496 the results of such procedure. **Figure 14** shows the resulting capacity curve.

497 **Table 5** – Main data of the DBA-ECSM procedure.
 498 (*) failure of the connections for Case Study A and of the column base for Case Study B

Case Study	Storey	Yielding of connection			Yielding of column base			Failure		
		$\Delta_{i,\text{conn}}$ (mm)	$\varphi_{i,\text{conn}}$ (rad)	F_i (kN)	$\Delta_{i,\text{conn}}$ (mm)	$\varphi_{i,\text{conn}}$ (rad)	F_i (kN)	$\Delta_{i,\text{conn}}$ (mm)	$\varphi_{i,\text{conn}}$ (rad)	F_i (kN)
A	3	18.2	0.0023	6.3	163.4	0.0257	27.8	314.9	0.0425	27.8
	2	10.7	0.0025	3.3	87.9	0.0238	14.8	188.9	0.0406	14.8
	1	3.5	0.0020	1.0	26.2	0.0159	4.4	76.7	0.0328	4.4
B	3	4.3	0.0006	9.0	61.3	0.0098	82.0	287.6	0.0349	82.0
	2	2.4	0.0006	4.9	32.7	0.0090	43.6	183.9	0.0341	43.6
	1	0.8	0.0004	1.4	9.7	0.0059	12.9	85.1	0.0311	12.9

499



500 a)

b)

501

Figure 14 – DBA-ECSM capacity curve: a) Case Study A; b) Case Study B

502

The capacity curve is bilinearized and the yield and target displacements corresponding to the considered limit states are calculated. This allows defining the equivalent SDOF system (Table 1). Table 5 shows the properties of the equivalent SDOF system and the results of the DBA-ECSM procedure in terms of a_g .

504

505

506

Table 5 – DBA-ECSM: equivalent SDOF system properties and results

	Case Study A		Case Study B	
	No P-Δ	P-Δ	No P-Δ	P-Δ
$\Delta_{y, SDOF}$ (mm)	114.0	114.0	46.0	46.0
$V_{y, SDOF}$ (kN)	142.0	134.6	416.4	405.2
$\Delta_{u, SDOF}$ (mm)	243.8	245.6	222.7	222.9
$V_{u, SDOF}$ (kN)	140.8	125.9	415.5	341.9
$EVD_{r=0.05}$ (%)	15.76	15.83	21.04	21.05
k_{eff} (kN/mm)	577.6	512.6	1866.0	1534.1
m_{eff} (kN/g)	177.3	177.3	187.4	187.4
T_{eff} (sec)	3.48	3.70	1.99	2.19
η	0.69	0.65	0.62	0.54
a_g (g)	0.410	0.438	0.421	0.486

507 **7.2 DBA with the Pushover Method (DBA-PM)**

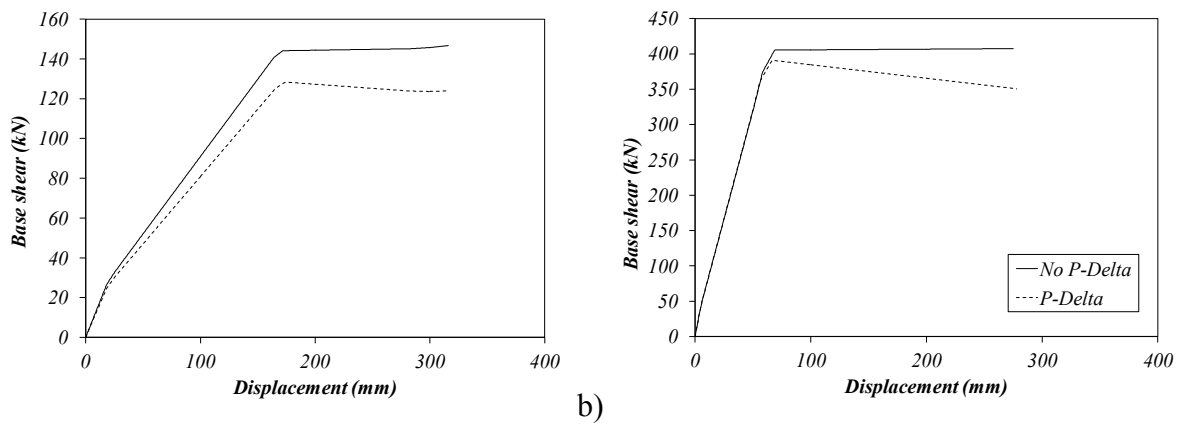
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The inelastic deflected shape of the system is obtained from a pushover analysis, similarly to typical non-linear static analyses. Figure 15 shows the resulting capacity curves. The properties of the equivalent SDOF structure are evaluated according to the aforementioned DBA procedure and reported in Table 4 along with the results of the DBA-PM procedure in terms of a_g .

510

511

512



513

a)

514

Figure 15 – DBA-PM capacity curve: a) Case Study A; b) Case Study B

515

Table 6 – DBA-PM: equivalent SDOF system properties and results

	Case study A		Case study B	
	No P- Δ	P- Δ	No P- Δ	P- Δ
$\Delta_{y, SDOF}$ (mm)	121.7	122.4	49.6	44.8
$V_{y, SDOF}$ (kN)	144.4	129.5	404.4	391.2
$\Delta_{u, SDOF}$ (mm)	243.1	242.6	214.6	216.1
$V_{u, SDOF}$ (kN)	146.7	123.9	407.5	350.6
$EVD_{\tau=0.05}$ (%)	15.10	15.01	20.55	21.03
k_{eff} (kN/mm)	603.5	510.8	1898.5	1622.8
m_{eff} (kN/g)	179.5	178.7	187.0	187.1
T_{eff} (sec)	3.43	3.72	1.97	2.13
η	0.70	0.67	0.63	0.55
a_g (g)	0.402	0.421	0.406	0.462

517 7.3 Validation by means of Incremental Dynamic Analyses (IDA)

518 Non-linear time history analyses have been carried out to validate the investigated DBA
 519 procedure. In particular, Incremental Dynamic Analyses have been conducted. The a_g values
 520 associated with the target limit states are estimated as the mean value of the results of time
 521 history analyses under 14 ground motions. The earthquake records² have been selected from the
 522 European strong-motion database (Ambraseys et al. 2002) in such a way to be spectrum
 523 compatible in displacement with EN 1998-1 type 1 spectrum ($a_g=0.300g$, $S=1.15$, $T_B=0.2$,
 524 $T_C=0.6$, $T_D=2$). **Figure 16** shows the displacement response spectrum of each record (GM), the
 525 resulting mean spectrum and the target spectrum.

526 The ground motion set has been incrementally scaled (i.e. the same additional scale factor is
 527 applied to each ground motion) to achieve the target limit state in the non-linear time history
 528 analyses. The selected limit state corresponds to the first collapse of a beam-column connection
 529 for Case Study A and to flexural failure of the base column for Case Study B. **Table 7** shows the
 530 results of the analyses in terms of a_g .

531

Table 7 – IDA results

	Limit state	a_{g_IDA} (No P- Δ) (g)	a_{g_IDA} (P- Δ) (g)
Case Study A	Failure of beam-column connection	0.398	0.393
Case Study B	Flexural failure at column base	0.491	0.480

532

² Waveform id according to Ambraseys et al. (2004). Scale factor in brackets.
 000343xa (1.250), 000244xa (1.455), 000472xa (0.978), 000302ya (1.565), 000644xa (0.867), 000359xa (1.470),
 000707ya (1.182), 000377ya (1.428), 001769ya (1.234), 005270xa (1.519), 001769ya (1.234), 005791ya (1.518),
 006960ya (0.827), 005815xa (1.484)

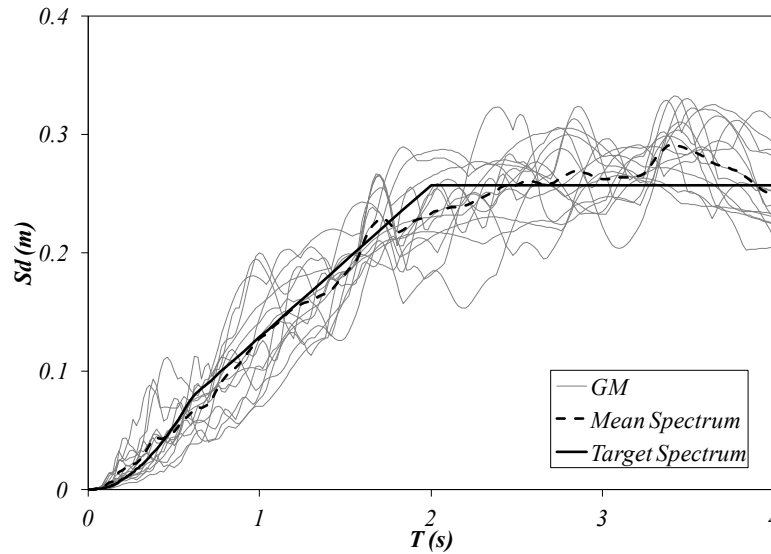


Figure 16 – Displacement spectrum of the selected ground motions.

Table 8 shows the comparison of the investigated DBA methods in dimensionless terms through the ratio between the DBA results (a_g) and the IDA results (a_{g_IDA}). Both DBA methods provide relatively good estimations, with a maximum error equal to 17% and 12% for Case Study B and A, respectively. It is worth noting that, for the considered case studies, DBA-ECSM leads to quite similar results compared to DBA-PM. In addition, a maximum 16% difference was recorded for ECSM when the influence of the second mode of vibration was not considered.

Table 8 – Results comparison: a_g/a_{g_IDA}

	Case study A		Case study B	
	No P- Δ	P- Δ	No P- Δ	P- Δ
DBA – PM	1.01	1.07	0.83	0.96
DBA – ECSM	1.03	1.12	0.86	1.01

8. Conclusions

The paper presents a Displacement Based Assessment (DBA) methodology for the evaluation of the seismic vulnerability of existing precast frame structures. The procedure specifically relates the seismic assessment to the building lateral displacements. Considering the high deformability of precast buildings, combined with the high deformation demand in the beam-column connections, the displacement is a suitable seismic vulnerability indicator. Furthermore, the non-linearity of the system is directly accounted for by the equivalent viscous damping, without requiring the definition of a behaviour factor as in standard linear methods.

The proposed procedure follows the same framework developed in the Direct Displacement Based Design methodology and it can be applied in a different sequence of steps compared to what presented in the paper, to suit the engineer or structure in question, without affecting the

555 core principles of the approach. The definition of the inelastic displacement profile is the major
556 difficulty in the development of the method, since the non-linear behaviour of the elements,
557 particularly beam-column connections, strongly affects the displacement distribution along the
558 building height. Two different solutions are proposed: the Pushover based Method (PM) and the
559 Equivalent Column Simplified Method (ECSM). Both approaches allow the definition of the
560 inelastic displacement profile, considering the non-linearity associated with structural elements
561 and connections, although ECSM is based on a simplified definition of the displacement profile
562 which can be implemented in spreadsheets.

563 The procedure is further refined including the influence of P- Δ effects and of the second mode of
564 vibration of the structure. P- Δ effects are accounted for by modifying the equivalent viscous
565 damping of the equivalent SDOF system. The second mode of vibration may be considered by
566 introducing the corresponding elastic forces combined with the forces associated with the first
567 mode of vibration. If the second mode of vibration is neglected, the assessment procedure may
568 underestimate the rotation of beam-column connections.

569 The proposed procedure has been validated by means of non-linear time history analyses
570 (incremental dynamic analyses). Two case studies have been selected resembling 3-storey
571 precast concrete frames. The DBA provides an approximate estimate of the building response if
572 compared to the results of incremental dynamic analyses: the maximum errors are 17% and 12%
573 for Case Study A and B, respectively. Finally, it is worth noting that, for the considered case
574 studies, DBA-ECSM leads to quite similar results compared to DBA-PM, therefore providing a
575 useful assessment tool for a first estimate of the seismic vulnerability.

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584

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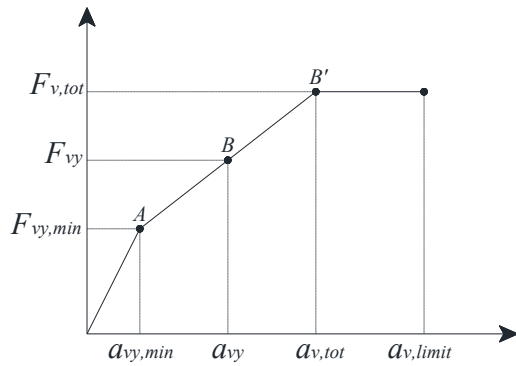
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699 **Appendix**

700 In this section, the shear-displacement relationship of dowel beam-column connections is
 701 presented following the formulation proposed by Ferreira (1999). A tri-linear force-displacement
 702 curve is obtained from defining the connection yielding, the maximum shear capacity of the
 703 dowels and the ultimate displacement. **Figure A1** shows the curve whose main points will be
 704 described later. The procedure is applied to the beam-column connection of Case Study A
 705 (properties shown in **Table A1**).
 706



Where:

$$a_{vy,min} = \lambda_{\tau,lig} \cdot F_{vy,min}$$

$$a_{vy} = \alpha_{crit} \cdot l_p = \alpha_{crit} \cdot (x_1 + x_2 + h_n)$$

B' = extrapolated from line A-B

707 **Figure A1** – Force-displacement relationship for dowel connections.

708 **Table A1** – Properties of the beam-column connection of Case Study A

Geometry	Concrete and grout	Neoprene	Dowels
Beam section: 30x50 cm	Concrete compressive strength $f_{ck,min} = 40$ MPa	Plan geometry: 30x15 cm	Tensile strength: $f_{yk} = 340$ MPa
Gap between beam and column: $gap = 2$ cm	Grout compressive strength $f_{ck,max} = 59$ MPa	thickness: $h_n = 0.5$ cm	Number of dowels: $n = 2$
Length of the corbel $L = 40$ cm		shear modulus: $G_{neo} = 1$ MPa	Diameter: $d_b = 12$ mm

709 The procedure assumes that the post-tension of the dowels leads to a reduced steel strength
 710 ($f_{sy,red}$):
 711

$$712 \quad f_{sy,red} = 0.7 \cdot f_{y,k} = 0.70 \cdot 340 = 238 \text{ MPa} \quad (\text{A.1})$$

713 The relative stiffness coefficient (Ferreira 1999) of the dowels embedded in the concrete and in
 714 the grout are calculated, respectively $k_{c,min}$ and $k_{c,max}$:

$$715 \quad k_{c,min} = 127 \cdot \frac{\sqrt{f_{ck,min}}}{d_b^{2/3}} = 127 \frac{\sqrt{40}}{12^{2/3}} = 153.24 \text{ MPa / mm} \quad (\text{A.2})$$

$$716 \quad k_{c,\max} = 127 \cdot \frac{\sqrt{f_{ck,\max}}}{d_b^{2/3}} = 127 \frac{\sqrt{59}}{12^{2/3}} = 186.11 \text{ MPa/mm} \quad (\text{A.3})$$

717 The following parameters are calculated according to the theory of a beam resting on an elastic
718 foundation:

$$719 \quad \alpha_{\min} = \sqrt[4]{\frac{k_{c,\min} \cdot d_b}{4 \cdot E_s \cdot I_b}} = \sqrt[4]{\frac{153.24 \cdot 12}{4 \cdot 210000 \cdot 1017.88}} = 0.0383 \quad (\text{A.4})$$

$$720 \quad \alpha_{\max} = \sqrt[4]{\frac{k_{c,\max} \cdot d_b}{4 \cdot E_s \cdot I_b}} = \sqrt[4]{\frac{1186.11 \cdot 12}{4 \cdot 210000 \cdot 1017.88}} = 0.0402 \quad (\text{A.5})$$

721 where E_s is the steel elastic modulus and I_b the second moment of area of the dowel.

722 The global deformability of the connection ($\lambda_{\tau,lig}$) is evaluated considering the contribution of the
723 dowel embedded in the concrete, the dowel embedded in the grout and the elastomeric cushion:

$$724 \quad \lambda_{\tau,lig} = \left[\frac{G_{neo} \cdot A_0}{h_n} + (n \cdot E_s \cdot I_b) \cdot \left(\frac{h_n^3}{12} + \frac{1}{3.5 \cdot \alpha_{\min}^3} + \frac{1}{3.5 \cdot \alpha_{\max}^3} \right)^{-1} \right]^{-1} =$$

$$= \left[\frac{1 \cdot 45000}{5} + (2 \cdot 210000 \cdot 1017.88) \cdot \left(\frac{5^3}{12} + \frac{1}{3.5 \cdot 0.0383^3} + \frac{1}{3.5 \cdot 0.0402^3} \right)^{-1} \right]^{-1} = \quad (\text{A.6})$$

$$= 18.51 \cdot 10^{-6} \text{ mm/N}$$

725 G_{neo} , A_0 and h_n are the shear modulus, the bearing area and the thickness of the elastomeric
726 cushion, n is the number of dowels.

727 Point A and B in Figure A1 are related to considerations of dowels embedded in the mortar
728 ($F_{vy,min}$) and in the concrete (F_{vy}), respectively. Those values are obtained from the following
729 calculations:

$$730 \quad \varepsilon_{\min} = \frac{3 \cdot e}{d_b} \cdot \sqrt{\frac{f_{ck,\min}}{f_{sy,red}}} = \frac{3 \cdot 2.5}{12} \cdot \sqrt{\frac{40}{238}} = 0.256 \quad (\text{A.7})$$

$$731 \quad C_{e,\min} = \sqrt{1 + (\varepsilon_{\min} \cdot C_{1,\min})^2} - \varepsilon_{\min} \cdot C_{1,\min} =$$

$$= \sqrt{1 + (0.256 \cdot 1.18)^2} - 0.256 \cdot 1.18 = 0.7424 \quad (\text{A.8})$$

$$732 \quad F_{vy,\min} = C_r \cdot C_{e,\min} \cdot C_{1,\min} \cdot n \cdot d_b^2 \cdot \sqrt{f_{ck,\min} \cdot f_{sy,red}} =$$

$$= 1 \cdot 0.7424 \cdot 1.18 \cdot 2 \cdot 12^2 \cdot \sqrt{40 \cdot 238} = 24616 \text{ N} \quad (\text{A.9})$$

$$733 \quad \varepsilon_{\max} = \frac{3 \cdot e}{d_b} \cdot \sqrt{\frac{f_{ck,\max}}{f_{sy,red}}} = \frac{3 \cdot 2.5}{12} \cdot \sqrt{\frac{59}{238}} = 0.3112 \quad (\text{A.10})$$

$$734 \quad C_{e,\max} = \sqrt{1 + (\varepsilon_{\max} \cdot C_{1,\max})^2} - \varepsilon_{\max} \cdot C_{1,\max} =$$

$$= \sqrt{1 + (0.3112 \cdot 1.25)^2} - 0.3112 \cdot 1.25 = 0.6840 \quad (\text{A.11})$$

$$\begin{aligned}
735 \quad F_{vy} &= C_r \cdot C_{e,max} \cdot C_{1,max} \cdot n \cdot d_b^2 \cdot \sqrt{f_{ck,max} \cdot f_{yk}} = \\
&= 1 \cdot 0.6840 \cdot 1.25 \cdot 2 \cdot 12^2 \cdot \sqrt{59 \cdot 250} = 29180 \text{ N}
\end{aligned} \tag{A.12}$$

736 where e is the eccentricity of the shear force and f_{yk} is the tensile strength of the dowels. C_r ,
737 $C_{1,max}$ and $C_{1,min}$ are constants (Ferreira, 1999) depending on the connection degree of fixity and
738 on the ultimate strength of grout/concrete.

739 The displacement $a_{v,min}$ is obtained from the global deformability of the connection and $F_{vy,min}$:

$$740 \quad a_{v,min} = \lambda_{\tau,lig} \cdot F_{vy,min} = 18.5 \cdot 10^{-6} \cdot 24616 = 0.46 \text{ mm} \tag{A.13}$$

741 The length of the plastic hinge (l_p) in dowels is a function of the reduced steel strength ($f_{sy,red}$):

$$742 \quad x_1 = \frac{\sqrt{f_{sy,red} / f_{ck,min}}}{3 \cdot C_{1,min}} \cdot d_b = \frac{\sqrt{238/40}}{3 \cdot 1.18} \cdot 12 = 8.27 \text{ mm} \tag{A.14}$$

$$743 \quad x_2 = \frac{\sqrt{f_{sy,red} / f_{ck,max}}}{3 \cdot C_{1,max}} \cdot d_b = \frac{\sqrt{238/59}}{3 \cdot 1.25} \cdot 12 = 6.43 \text{ mm} \tag{A.15}$$

$$744 \quad l_p = x_1 + x_2 + h_n = 8.27 + 6.43 + 5 = 19.70 \text{ mm} \tag{A.16}$$

745 The displacement associated with F_{vy} is obtained from:

$$746 \quad \alpha_{crit} = 1750 \cdot \frac{f_{sy,red}}{d_b \cdot E_s} = 1750 \cdot \frac{238}{12 \cdot 210000} = 0.165 \tag{A.17}$$

$$747 \quad a_{vy} = \alpha_{crit} \cdot l_p = 0.165 \cdot 19.70 = 3.26 \text{ mm} \tag{A.18}$$

748 The ultimate strength of the dowels is:

$$749 \quad F_{v,tot} = C_1 \cdot n \cdot d_b^2 \cdot \sqrt{f_{ck,max} \cdot f_{sy,red}} = 1.03 \cdot 2 \cdot 12^2 \cdot \sqrt{59 \cdot 238} = 35152 \text{ N} \tag{A.19}$$

750 The displacement associated with $F_{v,tot}$ is obtained from interpolation:

$$751 \quad \frac{29179 - 24616}{3.26 - 0.46} = \frac{35152 - 24616}{a_{v,tot} - 0.46} \Rightarrow a_{v,tot} = 6.92 \text{ mm} \tag{A.20}$$

752 Finally, the maximum displacement is assumed equal to the dowel diameter:

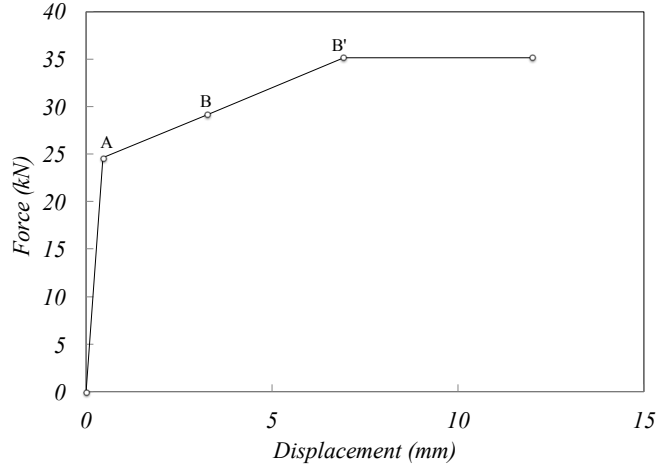
$$753 \quad a_{v,limit} = d_b = 12 \text{ mm} \tag{A.21}$$

754 **Figure A2** shows the resulting shear-displacement diagram.

755

756 The moment-rotation relationship is calculated for clockwise and counter-clockwise bending
757 moments, as described in section 4. The first step consists in the evaluation of the yield moment
758 ($M_y = 6.25\text{kNm}$) associated with yielding of the dowels obtained from a cross-section analysis.
759 The corresponding values of the neutral axis (x) and the axial strain in the dowels (ε_s) are 3.84cm
760 and 0.125%, respectively.

761



762
763 **Figure A2** – Force-displacement relationship for the connections of case study A

764 The axial deformation of the dowels associated with the applied post-tension is $\varepsilon_{s,post} = 0.0875\%$.
765 The corresponding rotation (φ_y) is obtained from considering a constant deformation along the
766 dowel length (l_s):

$$767 \quad \varphi_y = \varphi_y - \varphi_{y,post} = \frac{\varepsilon_s \cdot l_s}{d_s - x} - \frac{\varepsilon_{s,post} \cdot l_s}{d_s - x} = \quad (A.22)$$

$$= \frac{0.00125 \cdot 750}{150 - 38.37} - \frac{0.000875 \cdot 750}{150 - 38.37} = 2.52 \cdot 10^{-3} \text{ rad}$$

768 Similarly, the second step consists in the calculation of the ultimate moment ($M_u = 11.08\text{kNm}$),
769 the corresponding neutral axis ($x_u = 10.9\text{cm}$) and the dowel strain ($\varepsilon_{su} = 2.049\%$).

770 The corresponding rotation (φ_u) is:

$$771 \quad \varphi_u = \varphi_u - \varphi_{y,post} = \frac{\varepsilon_{su} \cdot l_s}{d_s - x_u} - \frac{\varepsilon_{s,post} \cdot l_s}{d_s - x} = \quad (A.23)$$

$$= \frac{0.02049 \cdot 750}{150 - 10.94} - \frac{0.000875 \cdot 750}{150 - 38.37} = 104.63 \cdot 10^{-3} \text{ rad}$$

772 For counter-clockwise rotations, the contact between the top of the beam and the side of the
773 column can be reached. The available rotation φ_{av} before contact is:

$$774 \quad \varphi_{av} = \frac{\text{gap}}{H + h_n} = \frac{20\text{mm}}{500\text{mm} + 5\text{mm}} = 39.60 \cdot 10^{-3} \text{ rad} \quad (A.24)$$

775 In this specific case the contact occurs after yielding and before reaching the ultimate moment,
776 therefore the bending moment corresponding to beam-column contact is obtained from
777 interpolation:

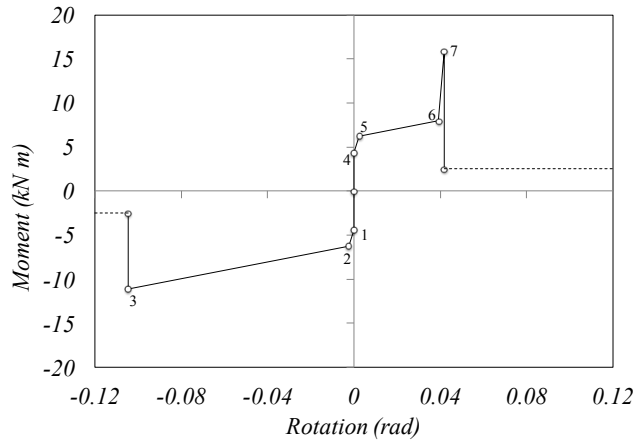
$$778 \quad \frac{M_{contact} - M_y}{\varphi_{av} + \varphi_y} = \frac{M_u - M_y}{\varphi_u + \varphi_y} \Rightarrow M_{contact} = 7.98 \text{ kNm} \quad (A.25)$$

779 After contact, the stiffness increases. The bending moment associated with dowel shear failure
780 ($F_{v,tot}$):

781
$$M_{post-contact} = F_{v,tot} \cdot 0.9 \cdot (h + e) = 35151 \cdot 0.9 \cdot (500 + 2.5) = 15.90 \text{ kNm} \quad (\text{A.26})$$

782 Finally, **Figure A3** shows the resulting moment-rotation curve considered in the analyses.

783



784

785

786

787

Figure A3 – Moment-rotation curve for beam-column connections of Case Study A
 Note: 1) loss of post-tension; 2) dowel yielding in tension; 3) dowel failure in tension;
 4) loss of post-tension; 5) dowel yielding in tension; 6) beam-column contact; 7) dowel failure in shear.